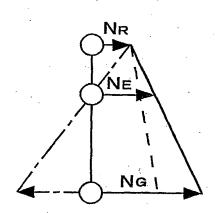
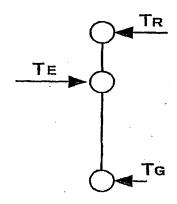


差 替 え 用 紙 (規則26)





23 FIG. 3



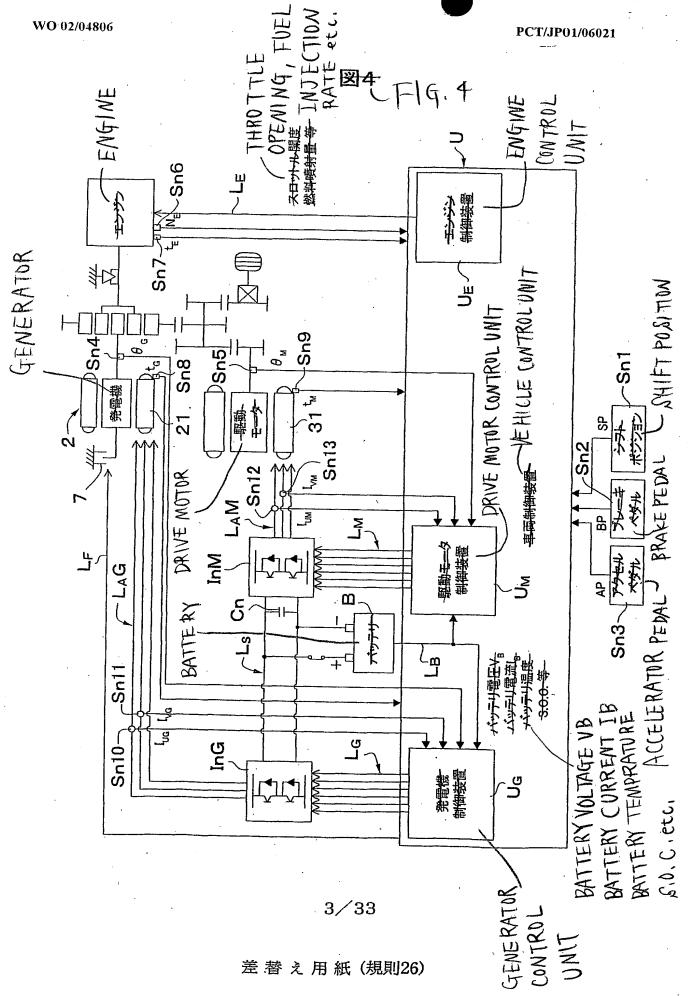
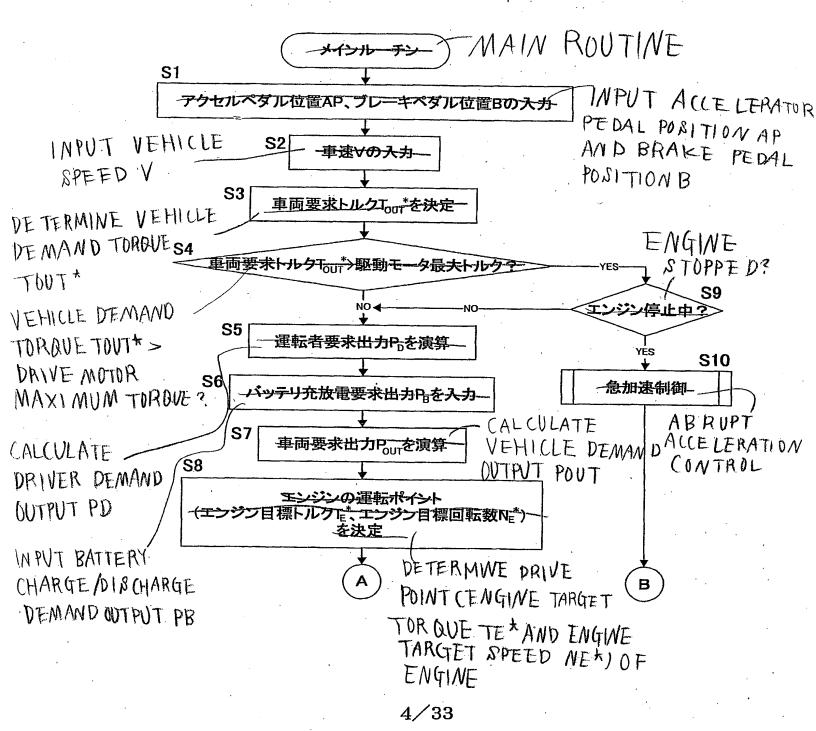
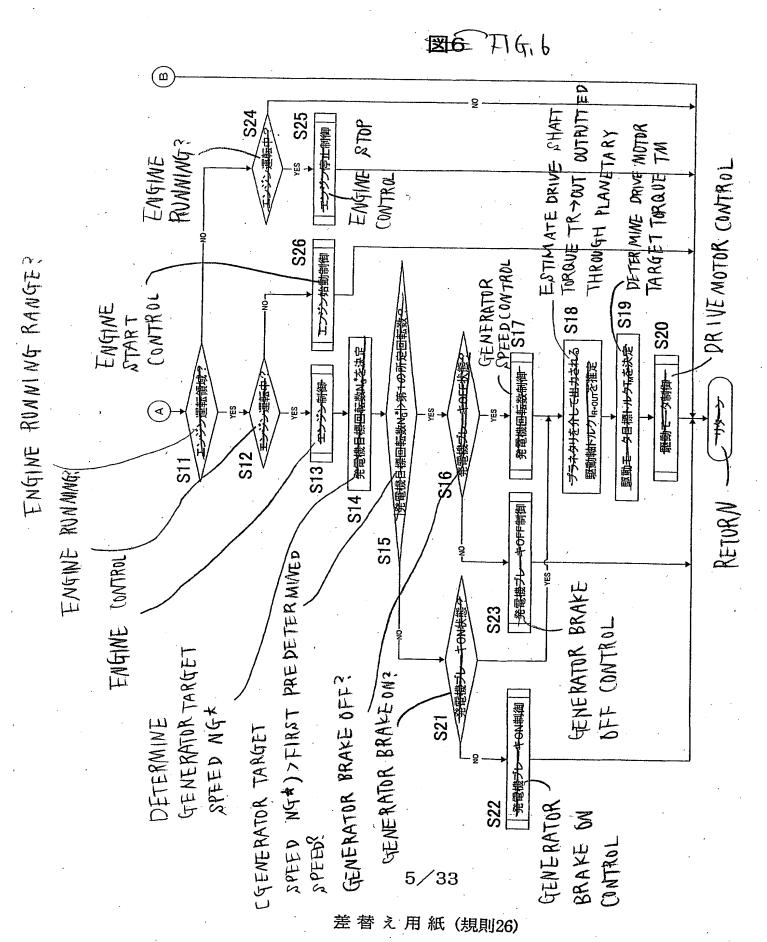
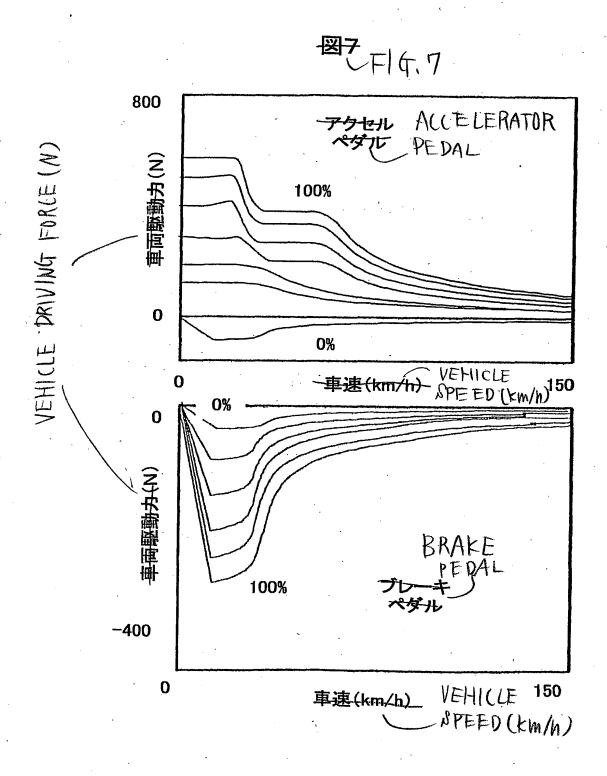
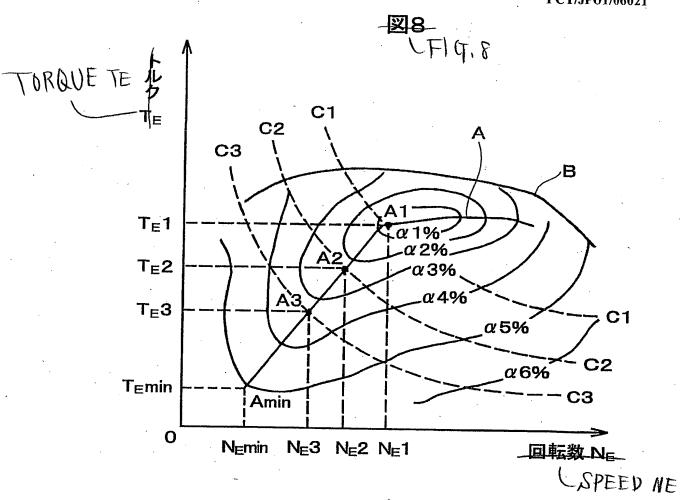


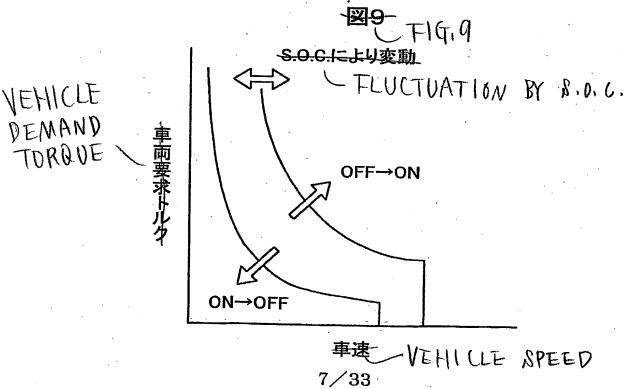
図5 F14.5

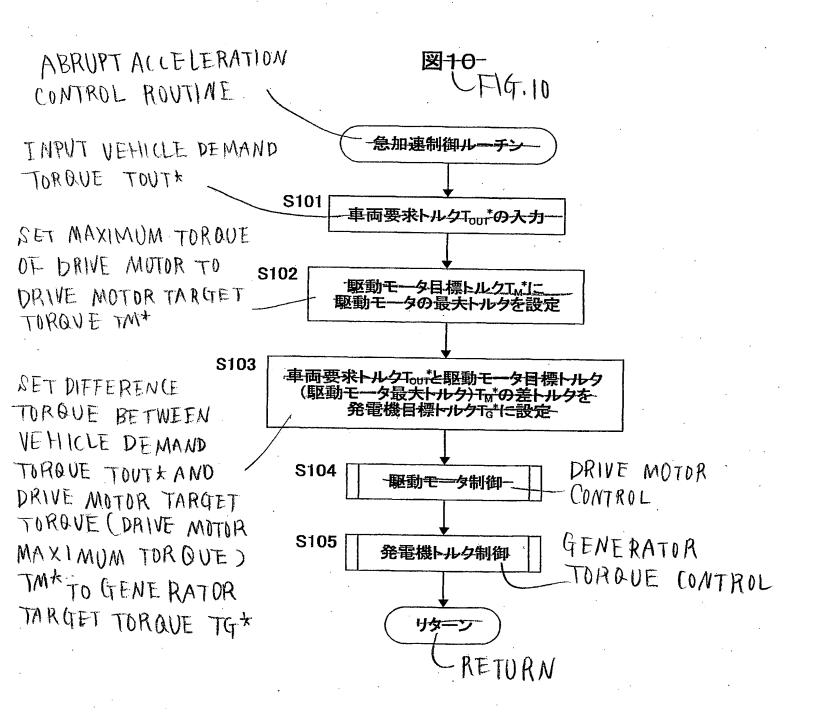


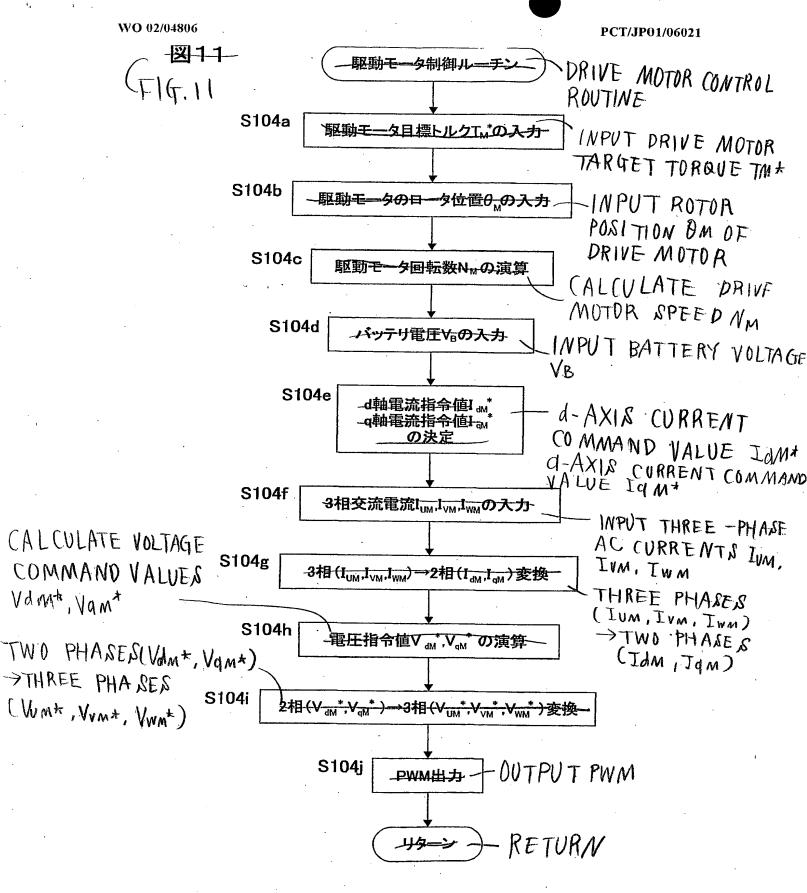






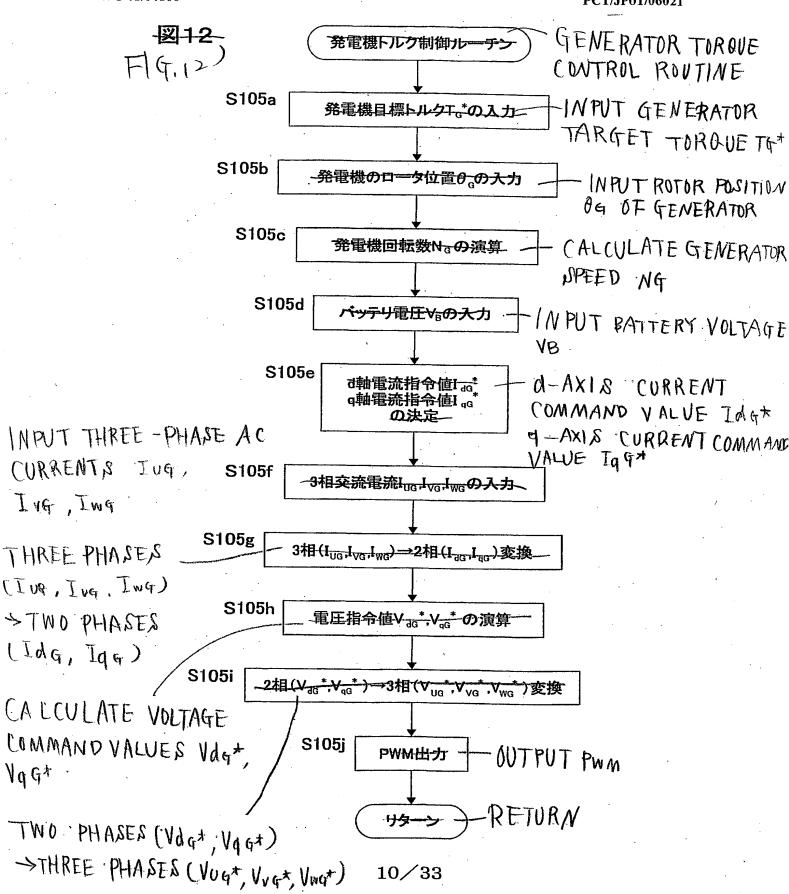


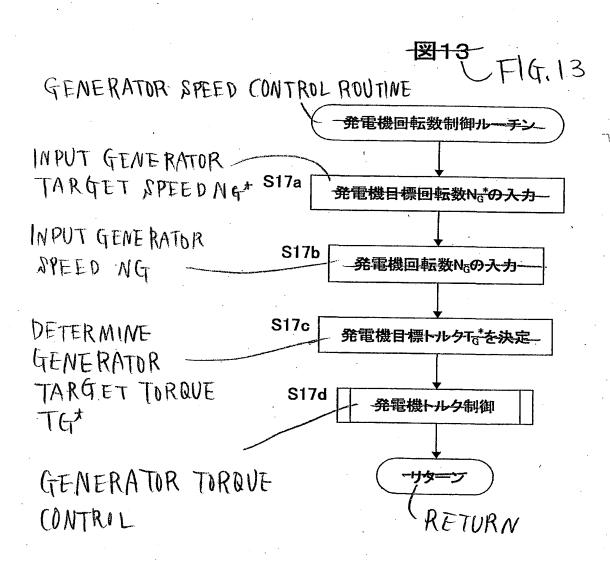




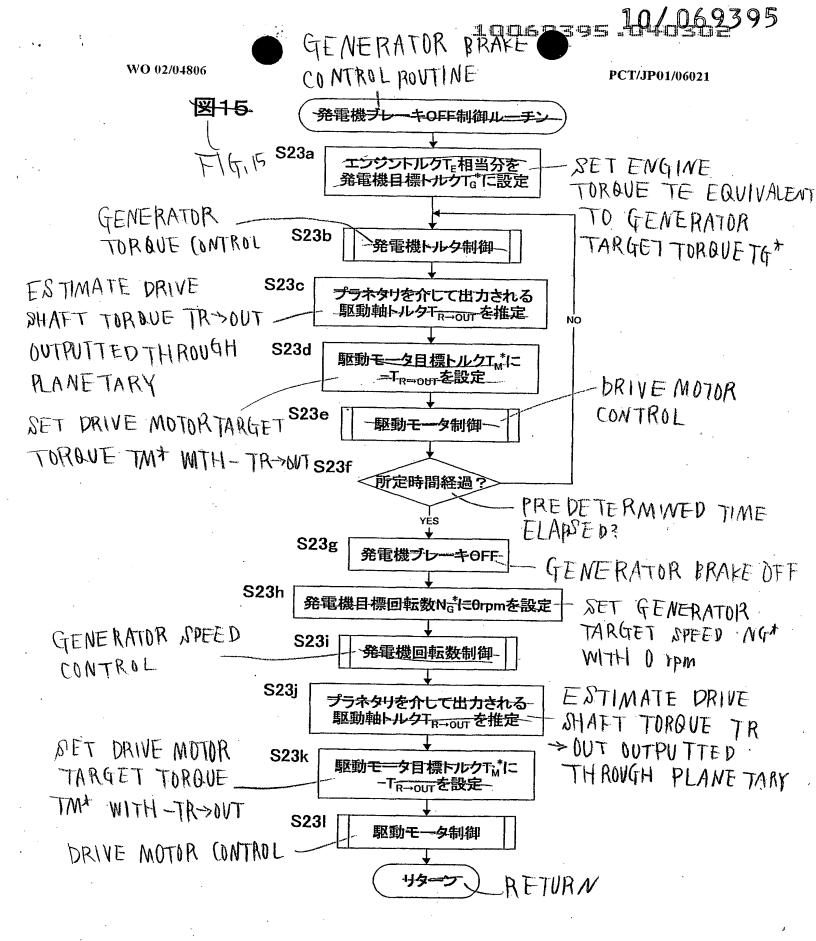
WO 02/04806 v

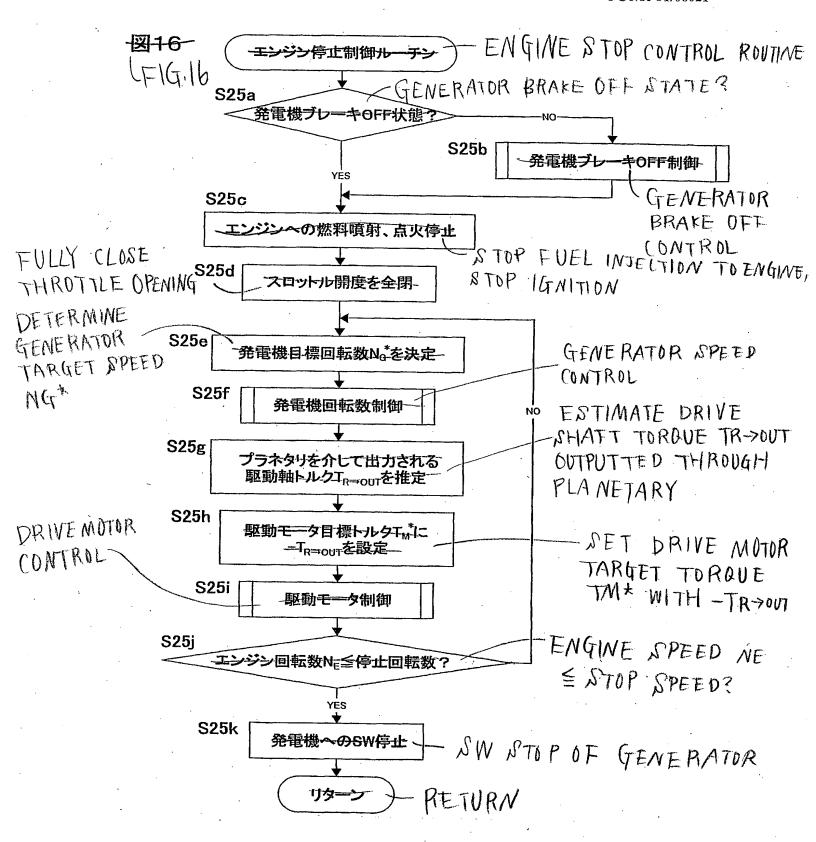
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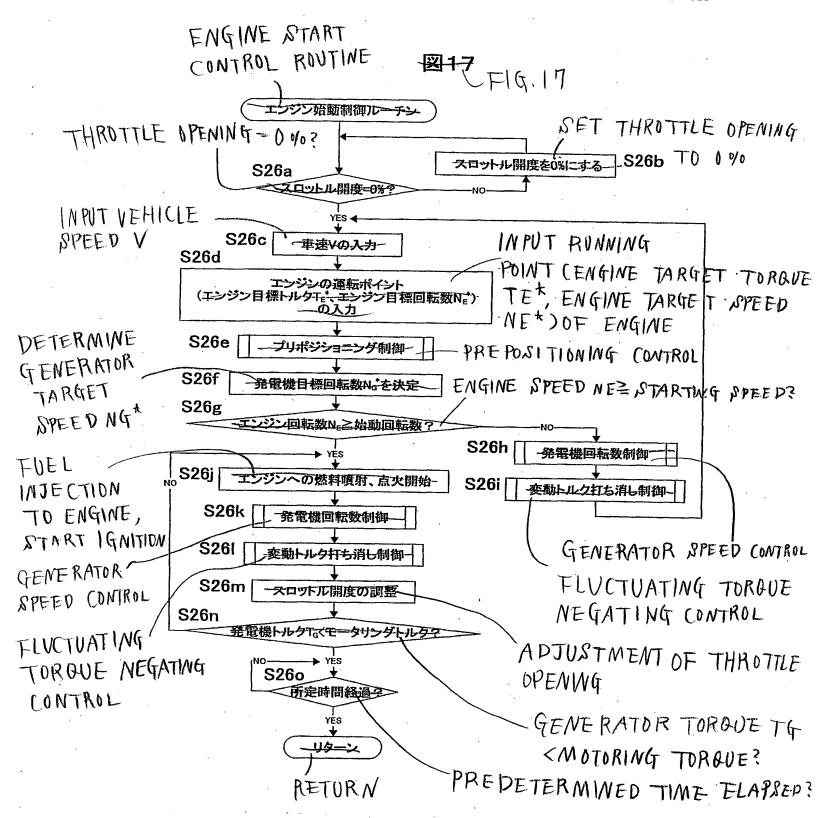


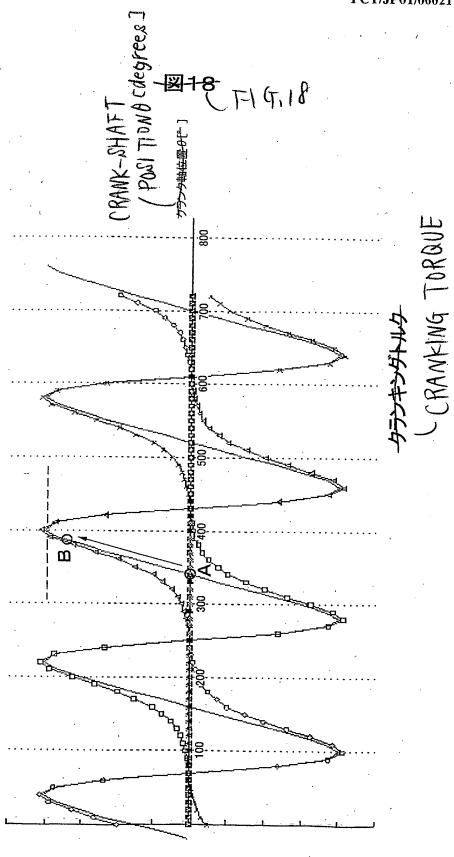


10062595 106989395 GENERATOR BRAKE ON WO 02/04806 CONTROL ROUTINE PCT/JP01/06021 JET FE NERATOR 図14 TARGET SPEED NG* F1G114 S22a WITH Orpm 発電機目標回転数Ng*IこOrpmを設定 GENERATOR SPEED S22b 発電機回転数制御 CONTROL SET DRIVE MOTOR TARGET S22c ESTIMATE DRIVE プラネタリを介して出力される TORO-UE TM+ 駆動軸トルクT_{R→OUT}を推定 SHAFT TORQUE TR WITH-TR->OUT S22d ->OUT OUT POTTED 駆動モータ目標トルタT_M*に =干R=OUT-を設定 THROUGH PLANETARY DRIVE MOTOR S22e 一夕制御一 CONTROL IGENERATOR SPEED NG] CATLOND PRE DETERMINES 22 F 発電機回転数N、K第2の所定回転数? SPEED? SET DRIVE MOTOR GENERATOR BRAKE ON-**S22g** 発電機ブレーキON CONTROL ESTIMATE DRIVE S22h プラネタリを介して出力される SHAFT TORQUE TR 駆動軸トルタエR一の出を推定 >OUT OUTPUTTED DRIVE MOTOR **S22i** THROUGH PLANETARY 駆動モータ目標トルクエボに CONTROL -T_{R→OUT}を設定 **S22**j 駆動モータ制御厂 PREDETERMINED TIME ELAPSED S22k 発電機ブレーキON状態で所定時間経過? IN. GENERATOR BRAKE ON? YES **S221** 発電機へのSW停止 STOP OF GENERATOR RETURN 12/33



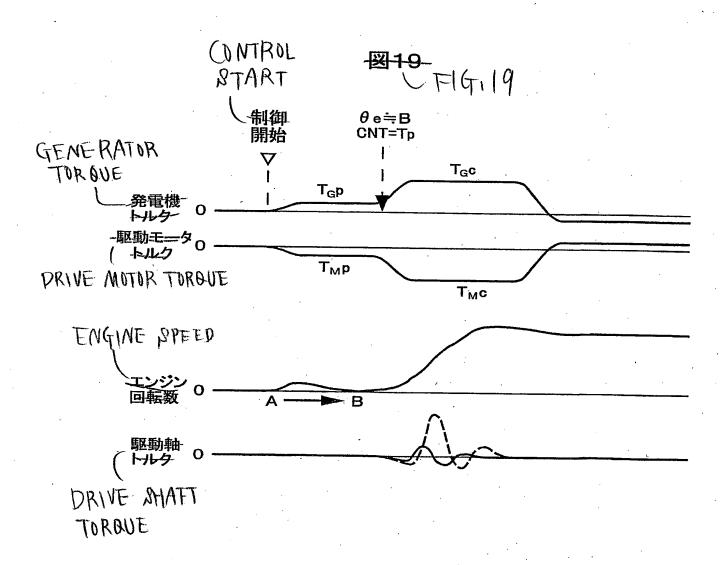


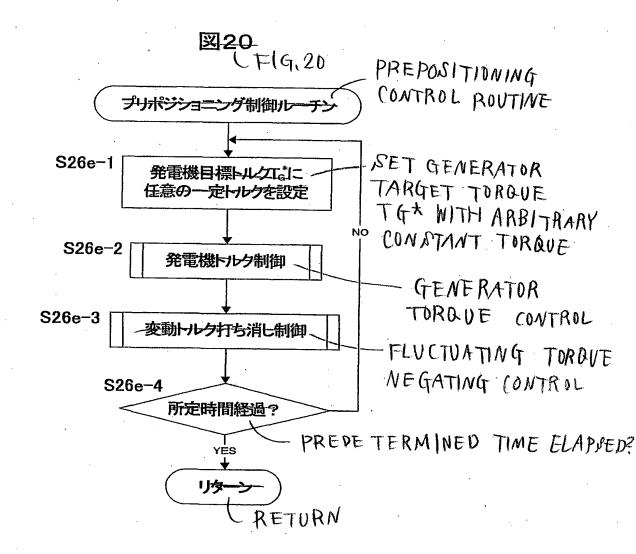


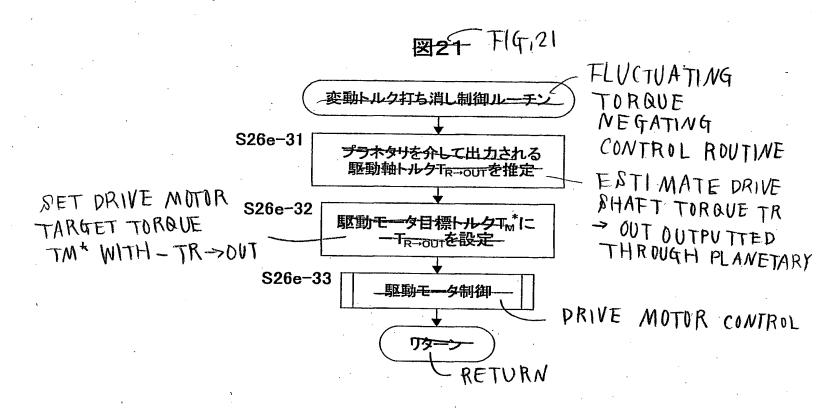


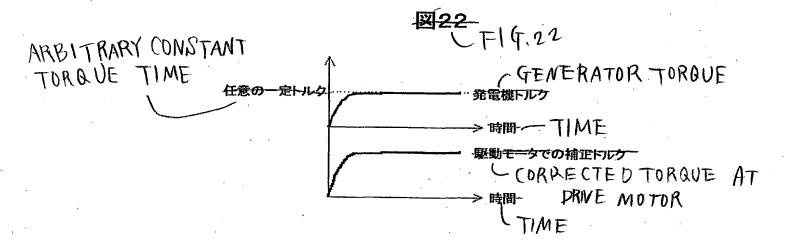
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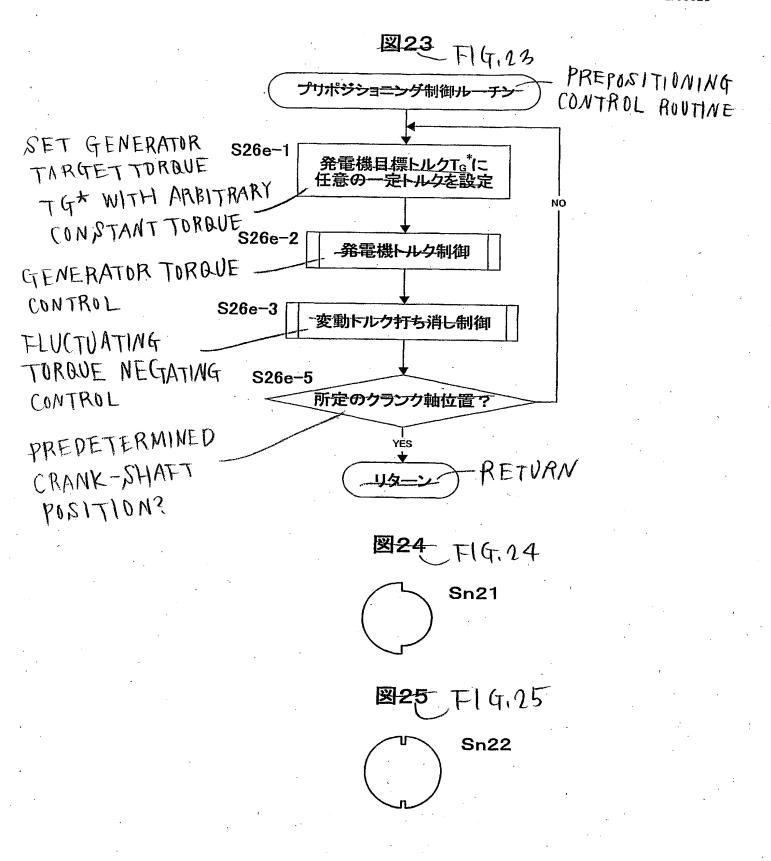
差替え用紙 (規則26)

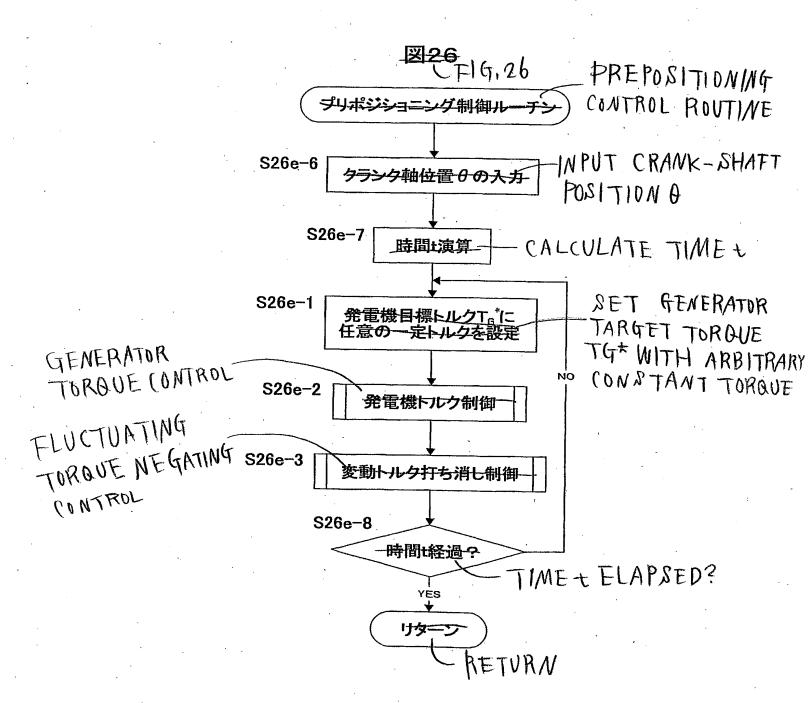


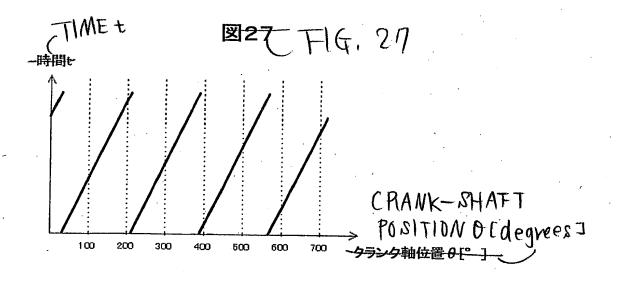


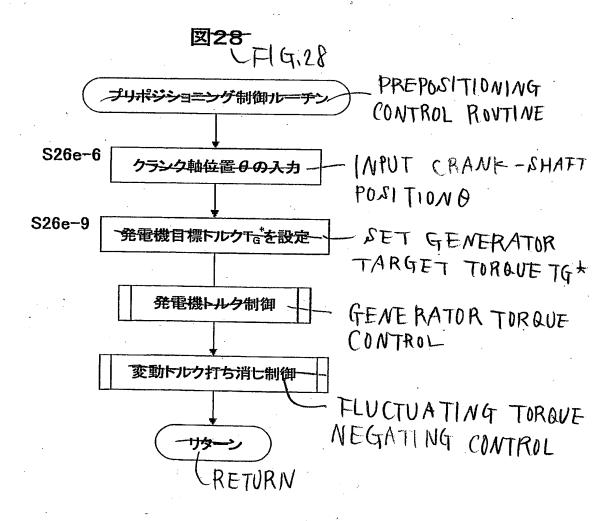


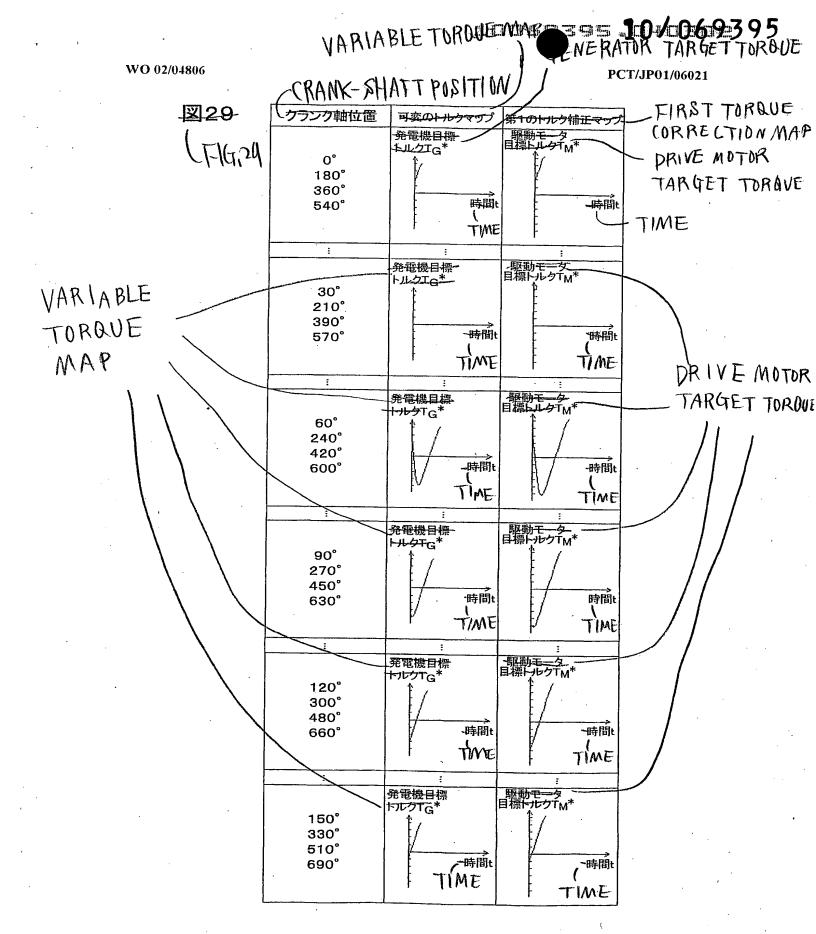






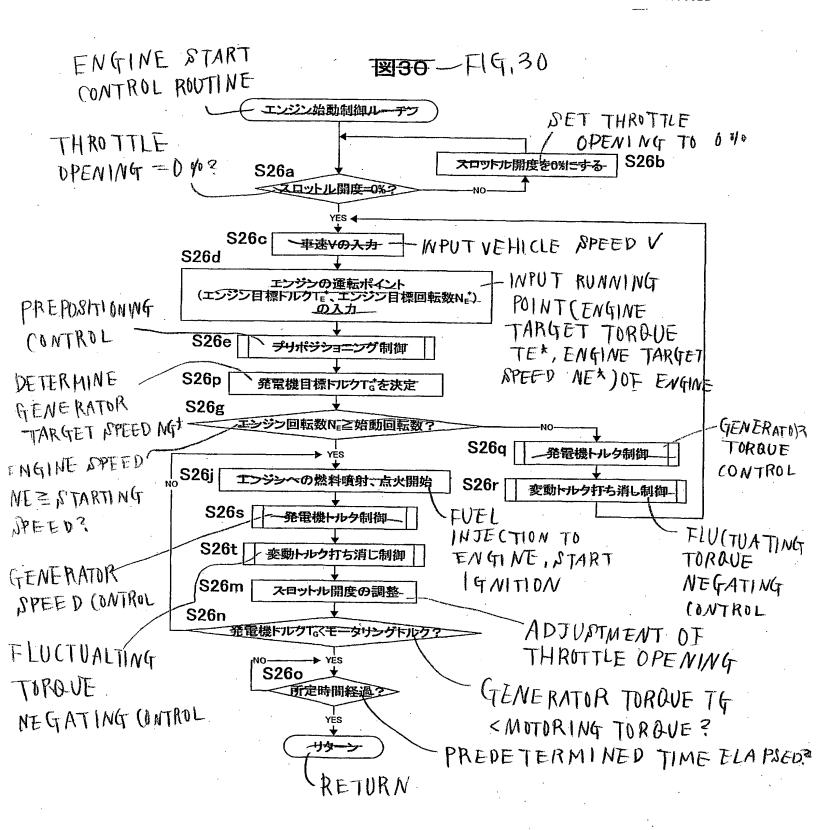


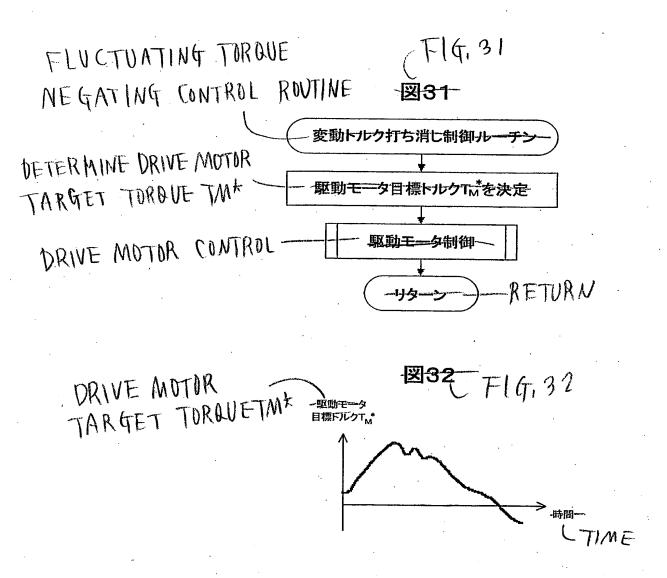


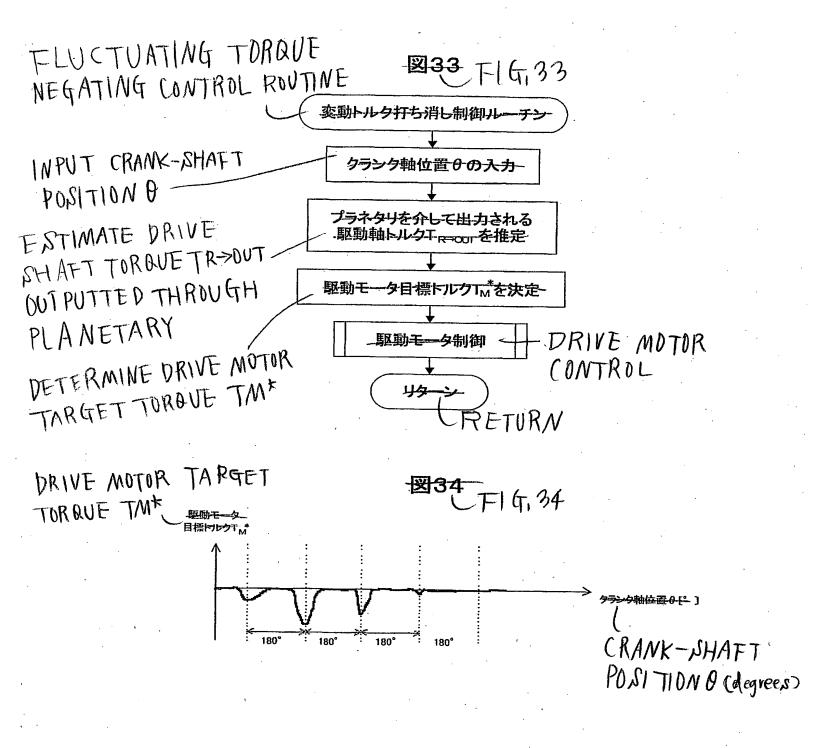


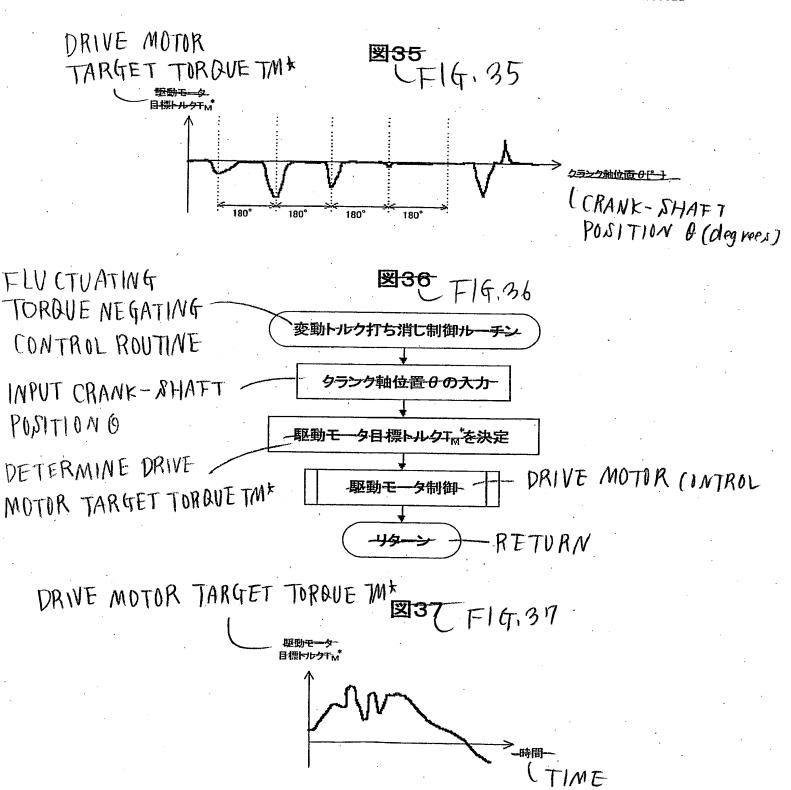
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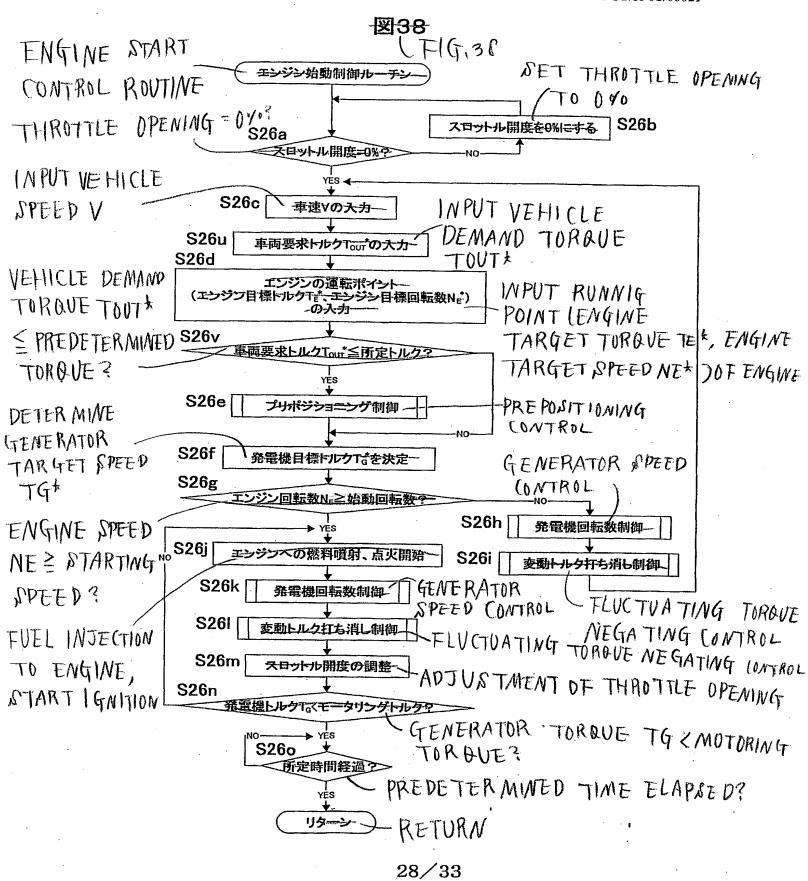
差替え用紙 (規則26)

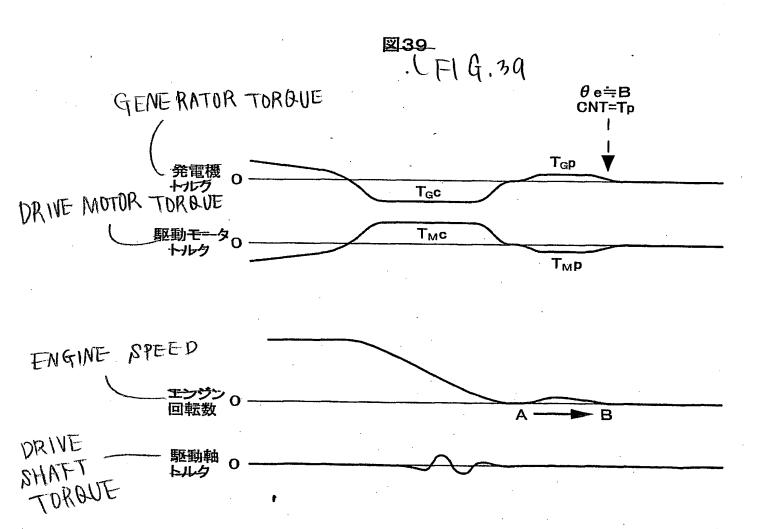


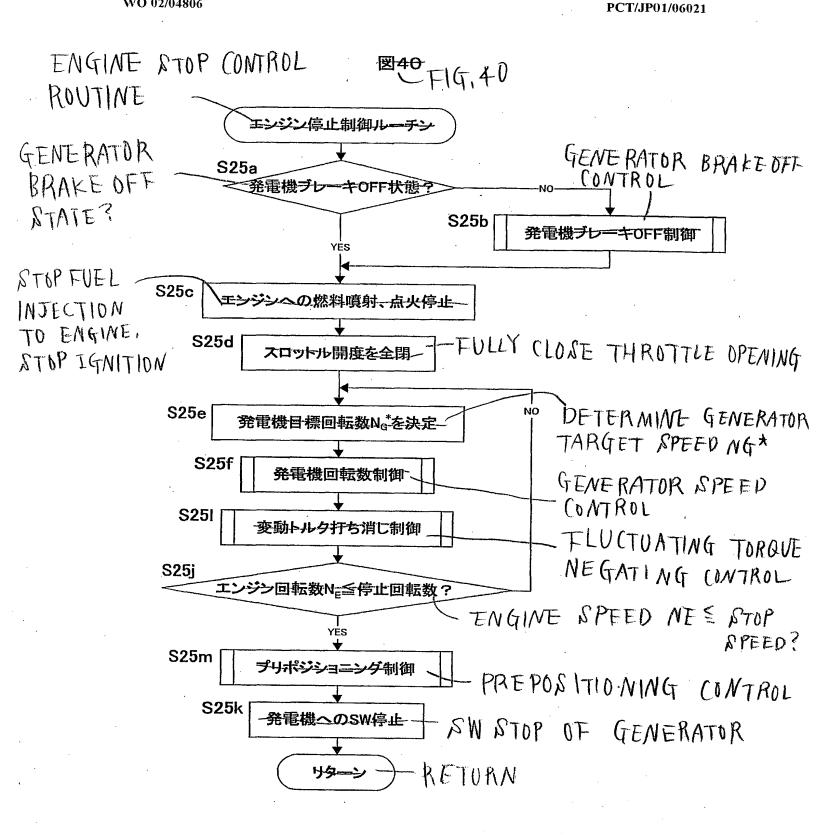


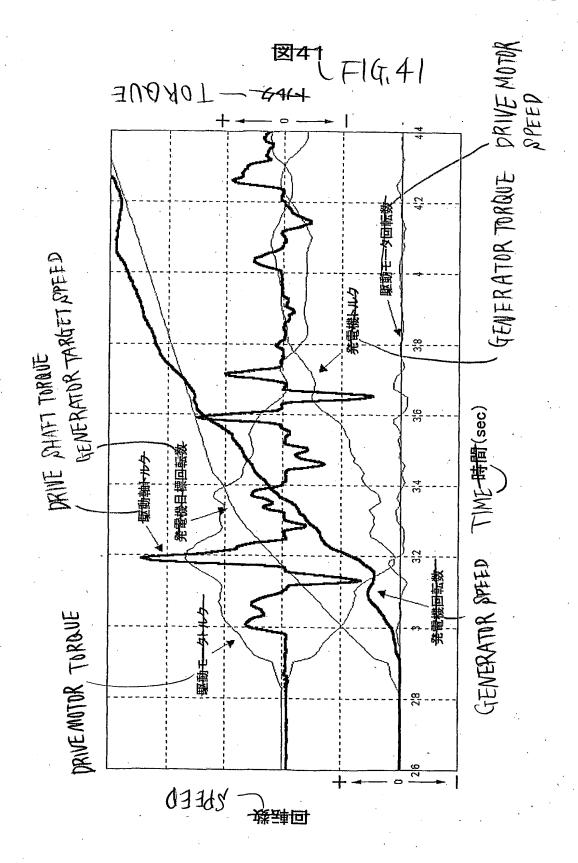






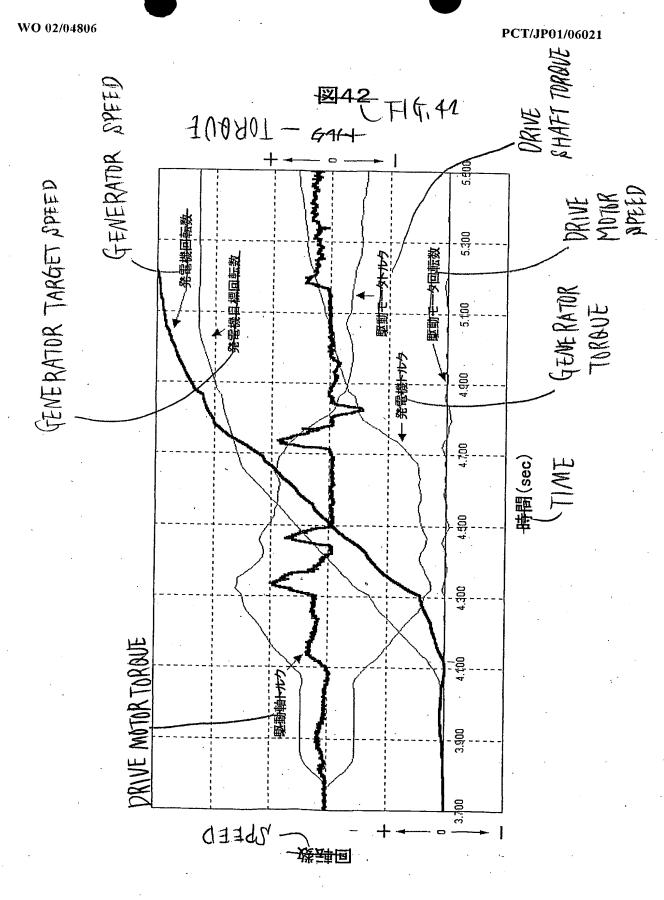






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差替え用紙 (規則26)



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差 替 え 用 紙 (規則26)

